## Handbook of Linear Algebra, 2nd Edition Errata List

## November 1, 2021

Changes are shown in red. Minor grammatical/spelling corrections do not appear on this list unless they could cause confusion.

- Ch. 0 p. 0-2. The definition of closed half plane should be: The closed left half-plane  $\mathbb{C}_0^-$  is  $\{z \in \mathbb{C} : \operatorname{re}(z) \leq 0\}$ .
- Ch. 0 p. 0-4. The definition of the gradient should be: The **gradient**  $\nabla f(\mathbf{x}_1, \ldots, \mathbf{x}_m)$  is the *n*-vector valued function with *i*th coordinate  $\frac{\partial f}{\partial x_i}$ .
- Ch. 0 p. 0-7. The definition of **big-theta** is wrong. It should be:  $f \text{ is } \Theta(g) \text{ (big-theta of } g) \text{ if } f \text{ is both } O(g) \text{ and } \Omega(g), \text{ i.e., there exist constants } c, C, k > 0$ such that  $c|g(x)| \leq |f(x)| \leq C|g(x)|$  for all  $x \geq k$ .
- Ch. 1 p. 1-4, line 2. This line should be: and a **column vector**, respectively, and they belong to  $F^{1 \times n}$  and  $F^{n \times 1}$ , respectively.
- Ch. 1 p. 1-10, line 2. This line should be:

in the same variables, such as  $\begin{array}{l}a_{11}x_1 + \dots + a_{1p}x_p = b_1\\a_{21}x_1 + \dots + a_{2p}x_p = b_2\\\dots\\a_{m1}x_1 + \dots + a_{mp}x_p = b_m\end{array}$ . A solution of the system is a

*p*-tuple

Ch. 1 p. 1-10, line 8. This line should be:

For the system 
$$\begin{array}{l} a_{11}x_1 + \dots + a_{1p}x_p = b_1 \\ a_{21}x_1 + \dots + a_{2p}x_p = b_2 \\ \dots \\ a_{m1}x_1 + \dots + a_{mp}x_p = b_m \end{array}, \text{ the } m \times p \text{ matrix } A = \begin{bmatrix} a_{11} & \dots & a_{1p} \\ \vdots & \dots & \vdots \\ a_{m1} & \dots & a_{mp} \end{bmatrix} \text{ is }$$

the

Ch. 2 p. 2-11, line 7. This line should be:

are the scalar coefficients  $c_1, c_2, \ldots, c_n \in F$  such that  $\mathbf{x} = c_1 \mathbf{b}_1 + c_2 \mathbf{b}_2 + \cdots + c_n \mathbf{b}_n$ .

Ch. 3 p. 3-2, Example 3.1.9. The following text should have been included. Here  $\mathbf{u} \times \mathbf{w}$  denotes the cross product of  $\mathbf{u}$  and  $\mathbf{w}$ , i.e.,

 $\mathbf{u} \times \mathbf{w} = [u_2 w_3 - u_3 w_2, u_3 w_1 - u_1 w_3, u_1 w_2 - u_2 w_1]^T.$ 

Ch. 10 p. 10-5. The displayed equations in Fact 10.7 should be:

$$\rho = \max_{\mathbf{x} \ge 0} \min_{\{i:x_i > 0\}} \frac{(P\mathbf{x})_i}{x_i} = \max_{\mathbf{x} > 0} \min_i \frac{(P\mathbf{x})_i}{x_i} = \min_{\mathbf{x} > 0} \max_i \frac{(P\mathbf{x})_i}{x_i}$$

Note that  $= \min_{\mathbf{x} \ge 0} \max_{\{i:x_i > 0\}} \frac{(P\mathbf{x})_i}{x_i}$  should not be listed.

Ch. 10 p. 10-10. Fact 10.3.6(c) should be:

c)  $\rho < \mu$  if and only if  $P\mathbf{u} < \mu \mathbf{u}$  for some vector  $\mathbf{u} \ge 0$ .

Ch. 11 p. 11-8, lines -12 to -11. The definition of the Kronecker product should be: Let  $A \in F^{m \times n}$  and  $B \in F^{p \times q}$ . Then the **Kronecker product** (sometimes called the **tensor product**) of A and B, denoted  $A \otimes B$ , is the  $mp \times nq$  partitioned matrix

$$A \otimes B = \begin{bmatrix} a_{11}B & a_{12}B & \cdots & a_{1n}B \\ a_{21}B & a_{22}B & \cdots & a_{2n}B \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}B & a_{m2}B & \cdots & a_{mn}B \end{bmatrix}$$

Ch. 43 p. 43-12. Fact 43.9.2 should be:

2. (Ryser's formula) If  $A = [a_{ij}]$  is an  $n \times n$  matrix over a commutative ring,

$$per(A) = \sum_{r=1}^{n} (-1)^{n-r} \sum_{\alpha \in Q_{r,n}} \prod_{i=1}^{n} \sum_{j \in \alpha} a_{ij}$$

- Ch. 14 p. 14-2. Fact 14.3 should be (repeated index has been deleted):
  - 3. If  $\varphi$  is a (p+q)-linear map from  $W_1 \times \cdots \times W_p \times V_1 \times \cdots \times V_q$  into U, then for every integer  $i, 1 \leq i \leq p$ , and  $\mathbf{w}_i \in W_i$ , the map  $\varphi_{\mathbf{w}_1,\ldots,\mathbf{w}_p}$  is a q-linear map.
- Ch. 47 p. 47-3. Fact 47.1.9 should be stated for graphs, not weighted graphs (the source [But08] states the result only for graphs and the proof provided here is valid only for graphs).

Ch. 71 p. 71-3, lines -14 to -11. The definition of a multivariate normal distribution should be: Then **x** is said to follow a **(nonsingular) multivariate normal distribution** when its pdf is

$$f(\mathbf{x}:\boldsymbol{\mu},\boldsymbol{\Sigma}) = (2\pi)^{-d/2} (\det \boldsymbol{\Sigma})^{-1/2} \exp\{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})\},\$$

where  $-\infty < x_j < \infty, \ j = 1, 2, ..., d$ .

Ch. 71 p. 71-5, lines 1–3. The definition of the likelihood function should be: the **likelihood function** is defined to be the joint pdf of the sample expressed as a function of the unknown parameters, namely,

$$L(\boldsymbol{\mu}, \Sigma) = \prod_{i=1}^{n} f(\mathbf{x}_i; \boldsymbol{\mu}, \Sigma).$$

Ch. 77 p. 7-2, lines 1–2. The definition of the impulse response should be:

The **impulse response** of a linear time-invariant system is the output h that results from applying as input the unit impulse  $\delta$  where  $\delta(0) = 1$  and  $\delta(k) = 0$  for  $k \neq 0$ .