

Numerical solution of time domain boundary integral equations

Penny J Davies
 Department of Mathematics
 University of Strathclyde

penny@maths.strath.ac.uk

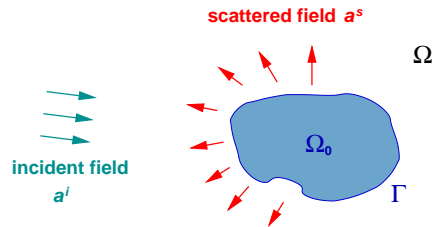
www.maths.strath.ac.uk/~aas96109/

Overview

- The problem (mainly acoustic scattering with Dirichlet BC)
- Collocation approximation (Dundee group)
- Galerkin approximation (French group)
- Convolution quadrature (Lubich et al)
- Fast plane wave methods (Michielssen et al)
- Fourier analysis
- Higher order methods
- **Good survey articles on TD BIEs:**
 - Tuong Ha Duong (2003)
 - Martin Costabel (2004)

Acoustic wave equation

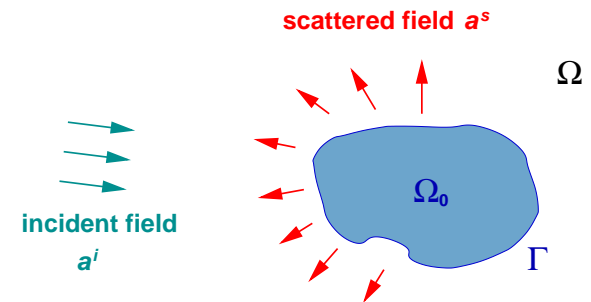
Problem: $a^i(x, t)$ is incident on Γ — find the scattered field $a^s(x, t)$



Incident field a^i :

- $a_{tt}^i = \Delta a^i$ in \mathbb{R}^3 (wave speed is $c = 1$);
- e.g. $a^i(x, t) = f(\nu \cdot x - t)$ where f has compact support and $|\nu| = 1$ (often approximate by a Gaussian);
- assume a^i does not reach obstacle before time $t = 0$.

Equations for scattered field



- $a_{tt}^s = \Delta a^s$ in \mathbb{R}^3/Γ ;
- $a^s(x, t) = 0$ for $t \leq 0$ (causality);
- Dirichlet BC: $a^s + a^i = 0$ on Γ (“sound soft” case).

- Scattered field (exterior):

$$\mathbf{a}^s(\mathbf{x}, t) = \frac{1}{4\pi} \int_{\Gamma} \frac{u(\mathbf{x}', t - |\mathbf{x}' - \mathbf{x}|)}{|\mathbf{x}' - \mathbf{x}|} dS_{\mathbf{x}'} \quad \mathbf{x} \in \Omega, t > 0$$

- The surface potential u satisfies:

$$\frac{1}{4\pi} \int_{\Gamma} \frac{u(\mathbf{x}', t - |\mathbf{x}' - \mathbf{x}|)}{|\mathbf{x}' - \mathbf{x}|} dS_{\mathbf{x}'} = -\mathbf{a}^i(\mathbf{x}, t) \quad \mathbf{x} \in \Gamma, t > 0. \quad (*)$$

IC: $u \equiv 0$, $\mathbf{a}^i \equiv 0$ on Γ for all $t \leq 0$ (causality).

- Need to solve BIE (*) for $u(\mathbf{x}, t)$ on $\Gamma \times (0, T)$.

Find u given a on $\Gamma \times (0, T)$:

$$\int_{\Gamma} \frac{u(\mathbf{x}', t - |\mathbf{x}' - \mathbf{x}|)}{|\mathbf{x}' - \mathbf{x}|} dS_{\mathbf{x}'} = a(\mathbf{x}, t) \quad \mathbf{x} \in \Gamma, t > 0.$$

IC: $u \equiv 0$, $a \equiv 0$ on Γ for all $t \leq 0$ (causality).

- This is the **single layer potential equation** for acoustic scattering the (open or closed) surface Γ .
- It is a **retarded potential integral equation (RPIE)**.
- EM:** equations much more complicated but EFIE formulation for a perfect conductor also involves this RPIE.

Existence and uniqueness for BIE ...

... when Γ is **smooth and closed** (Bamberger and Ha Duong 1986, Lubich 1994) or **flat** (Ha Duong 1990, Lubich 1994).

$$\mathbf{BIE:} \int_{\Gamma} \frac{u(\mathbf{x}', t - |\mathbf{x}' - \mathbf{x}|)}{|\mathbf{x}' - \mathbf{x}|} dS_{\mathbf{x}'} = a(\mathbf{x}, t) \quad \mathbf{x} \in \Gamma, t > 0.$$

Flat plate result: If $a(\cdot, t) \in H^{1/2}(\Gamma)$ is smooth in time and vanishes near $t = 0$, there is a unique smooth solution $u(\cdot, t) \in H^{-1/2}(\Gamma)$ with

$$\|u\|_{H_*^m(0, T; H^{-1/2}(\Gamma))} \leq C \|a\|_{H_*^{m+1}(0, T; H^{1/2}(\Gamma))} \quad (m \in \mathbb{R}).$$

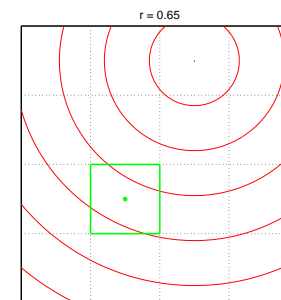
Notation: $H_*^m(0, T) = \{f|_{(0, T)} : f \in H^m(\mathbb{R}) \text{ with } f \equiv 0 \text{ on } (-\infty, 0)\}$

$$\|f\|_{H_*^m(0, T; X)}^2 = \sum_{k=0}^m \|\partial^k f / \partial t^k\|_{L^2(0, T; X)}^2, \quad \|f\|_{L^2(0, T; X)}^2 = \int_0^T \|f\|_X^2 dt$$

Numerical approx: collocation

- Approx u in time and space: $u(\mathbf{x}, t) \approx U(\mathbf{x}, t) = \sum_{k,m} U_k^m \phi_k(\mathbf{x}) \psi_m(t)$
- Suppose approx BIE holds at N_S points $\mathbf{x}_\beta \in \Gamma$ and times $t^n = n\Delta t$

$$\int_{\Gamma} \frac{U(\mathbf{x}', t^n - |\mathbf{x}' - \mathbf{x}_\beta|)}{|\mathbf{x}' - \mathbf{x}_\beta|} dS_{\mathbf{x}'} = a(\mathbf{x}_\beta, t^n), \quad n \leq N_T$$



$$\int_{\Gamma_\alpha} \frac{U(\mathbf{x}', t^n - |\mathbf{x}' - \mathbf{x}_\beta|)}{|\mathbf{x}' - \mathbf{x}_\beta|} dS_{\mathbf{x}'} = a(\mathbf{x}_\beta, t^n)$$

- Approx BIE:

$$\sum_{k,m} \int_{\Gamma} \frac{U_k^m \phi_k(\mathbf{x}') \psi_m(t^n - |\mathbf{x}' - \mathbf{x}_\beta|)}{|\mathbf{x}' - \mathbf{x}_\beta|} dS_{\mathbf{x}'} = a(\mathbf{x}_\beta, t^n)$$

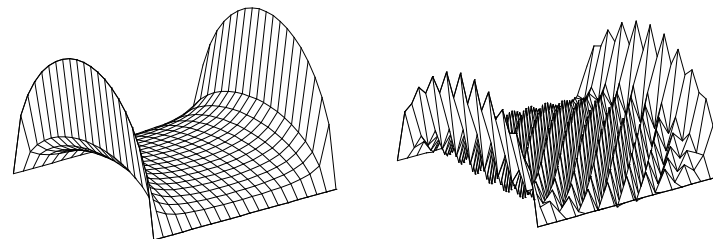
- Evaluate integrals:

$$\sum_{m=0}^n Q_m \underline{U}^{n-m} = \underline{a}^n$$

- Rearrange sum to get time-stepping algorithm

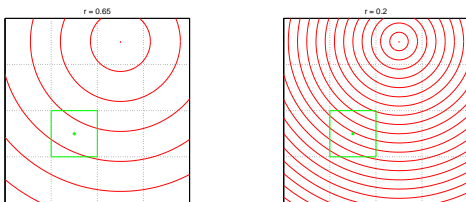
$$Q_0 \underline{U}^n = \underline{a}^n - \sum_{m=1}^{n-1} Q_m \underline{U}^{n-m}$$

for \underline{U}^n in terms of (very sparse) matrices $Q_m \in \mathbb{R}^{N_S \times N_S}$.



- Typical exponential oscillating instability (for EM) with $N_S = 20 \times 20$
- This scheme appears **completely stable** for smaller N_S (nasty!)
- Stability depends crucially on:
 - **time basis functions** (low order generally better)
 - **integral evaluation** (needs to be accurate)

$$\int_{\Gamma_\alpha} \underbrace{\frac{U(\mathbf{x}', t^n - |\mathbf{x}' - \mathbf{x}_\beta|)}{|\mathbf{x}' - \mathbf{x}_\beta|}}_R dS_{\mathbf{x}'} = a(\mathbf{x}_\beta, t^n)$$



- Patchwise high order quadrature isn't sensible for low order approx
- Methods based on **local polar coordinates** centred at \mathbf{x}_β can work well
- Can use exact integration (Stokes formula) on space–time patches

- Some key names: Nédélec, Ha Duong, Terrasse
- Some key papers: Bamberger & Ha Duong (1986), Ha Duong (1993, 2003), Terrasse (PhD thesis, 1993)
- Very nice theory, based on BIE as time convolution of integral operator on Γ
- **Prove stability** (under exact integration) for an approx with piecewise linears in time, piecewise constants in space.

BIE:
$$\int_{\Gamma} \frac{u(\mathbf{x}', t - |\mathbf{x}' - \mathbf{x}|)}{|\mathbf{x}' - \mathbf{x}|} dS_{\mathbf{x}'} = a(\mathbf{x}, t) \quad \mathbf{x} \in \Gamma, t > 0.$$

- Approx u in space (N_S basis functions, PWC) and time (N_T functions, PWL)
- Integrate BIE against test functions in time and space — 5D integrals over subregions of $\Gamma \times \Gamma \times (0, T)$ (use Stokes to reduce dimension)
- Again get time-stepping algorithm of the form

$$Q_0 \underline{U}^n = \underline{a}^n - \sum_{m=1}^{n-1} Q_m \underline{U}^{n-m}$$

with **very sparse** matrices Q_m

- **Lubich** (1994). Assume: a is smooth in time, vanishes near $t = 0$
- Take the Laplace transform of the BIE — gives single layer potential (SLP) equation for Helmholtz:

$$\int_{\Gamma} K(\mathbf{x} - \mathbf{x}', s) \bar{u}(\mathbf{x}', s) dS_{\mathbf{x}'} = \bar{a}(\mathbf{x}, s), \quad K(\mathbf{x}) = e^{i s |\mathbf{x}| / |\mathbf{x}'|}$$

- Use Galerkin approximation in space for SLP.
- Convolution quadrature method: treat s like $\partial/\partial t$ and approx it by finite difference quotient from an A-stable LMM (highest order is BDF2)
- Gives (usual) time-stepping algorithm $Q_0 \underline{U}^n = \underline{a}^n - \sum_{m=1}^{n-1} Q_m \underline{U}^{n-m}$ but now for **full** matrices Q_m .
Operations count: $O(N_S^2 N_T^2)$

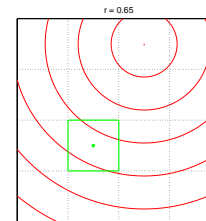
- “Raw” version:

$$Q_0 \underline{U}^n = \underline{a}^n - \sum_{m=1}^{n-1} Q_m \underline{U}^{n-m}$$

in $O(N_S^2 N_T^2)$ flops.

- Lubich (1994): can use FFT to speed up the recursive sums (Hairer, Lubich, Schlichte 1985) to give $O(N_S^2 N_T \log^2 N_T)$
- Hackbush, Kress, Sauter (preprint, 2006): introduce a ‘cut-off’ strategy to sparsify the matrices Q_m to facilitate panel clustering
- Note: Lubich shows that perturbing the matrices will still give a stable method (effect of perturbations not known for space–time Galerkin)

- **Collocation or Galerkin** (unknowns: N_S in space, N_T in time)



$$Q_0 \underline{U}^n = \underline{a}^n - \sum_{m=1}^{n-1} Q_m \underline{U}^{n-m}$$

RHS takes $O(N_S^2)$ flops per time-step

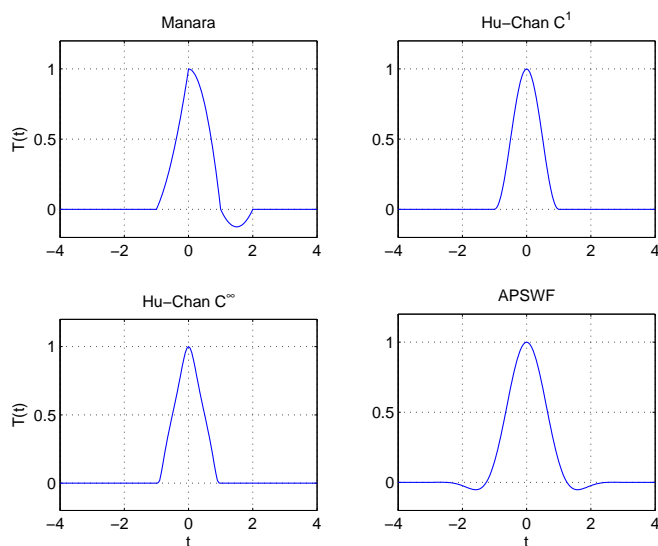
Total is $O(N_S^2 N_T)$

- **PDE approach** for acoustic wave equation: $O(N_S^{3/2} N_T)$
- **Convolution quadrature**
 - “raw”: $O(N_S^2 N_T^2)$
 - with Hairer–Lubich–Schlichte speed-up: $O(N_S^2 N_T \log^2 N_T)$
 - with sparsification + panel clustering(?): $O(\log^{11} N_S N_T^{9/2})$

- Michielssen and team have developed and implemented the **plane wave time domain (PWTD)** algorithm
- Time domain counterpart of the fast multipole method
- Expand u in terms of band limited functions in time
- Complicated, but fast!
 - two-level: $O(N_S^{3/2} N_T)$
 - multi-level: $O(N_S \log^2 N_S N_T)$
 - (compare with $O(N_S^2 N_T)$ for standard collocation or Galerkin)

- Many different approaches have been used by (mainly) engineers. much (any?) analysis.
- **global basis functions** e.g. Chung, Sarkar et al: Laguerre polynomials
- **local basis functions**
 - Manara: piecewise quadratic
 - Hu and Chan: based on $\cos^2 t$
 - Hu and Chan: based on C^∞ exponential
 - Michielssen: approximate prolate spheroidal wave functions

$$T(t) = \left(\frac{\sin s\omega_0 t}{s\omega_0 t} \right) \frac{\sin \left(a\sqrt{(t/N\Delta t)^2 - 1} \right)}{\sinh(a)\sqrt{(t/N\Delta t)^2 - 1}}$$



- BIE:

$$\int_{\mathbb{R}^2} \frac{u(\mathbf{x}', t^n - |\mathbf{x}' - \mathbf{x}|)}{|\mathbf{x}' - \mathbf{x}|} dS' = a(\mathbf{x}, t^n), \quad \mathbf{x} \in \mathbb{R}^2$$

- Continuous Fourier transform at frequency ω :

$$2\pi \int_0^{t^n} J_0(|\omega|R) \hat{u}(\omega, t^n - R) dR = \hat{a}(\omega, t^n), \quad \omega \in \mathbb{R}^2$$

- Approximation of BIE: $\sum_{m=0}^n Q_m \underline{U}^{n-m} = \underline{a}^n$

- Discrete Fourier transform (infinite mesh) at spatial frequency ω :

$$\sum_{m=0}^n q_m(\omega) \tilde{U}^{n-m}(\omega) = \tilde{a}^n(\omega), \quad \omega \in \left[\frac{-\pi}{\Delta x}, \frac{\pi}{\Delta x} \right]^2$$

• DFT convolution sum: $\sum_{m=0}^n q_m(\omega) \tilde{U}^{n-m}(\omega) = \tilde{a}^n(\omega)$

• Invert (e.g. by using Z -transforms):

$$\tilde{U}^n = \sum_{m=1}^{n-1} p_m \tilde{a}^{n-m}, \quad \text{where} \quad p_n = -q_0^{-1} \sum_{m=1}^n q_m p_{n-m}$$

stability is determined by the coefficients $|p_n(\omega)|$

- Need $|p_n(\omega)|$ to be bounded for all $\omega \in [-\pi/\Delta x, \pi/\Delta x]^2$ and all n .
- (Relatively) quick to compute, and seems to be a reliable test (ignoring edge effects)

- Most (all?) existing approx are low order in time and space
- **In space:** could use higher order polynomials away from edges (do not seem to affect stability for collocation)
- **In time:** need to be careful – stability very sensitive to time approx (collocation)
- Use Fourier transformed (in space) BIE to develop new time approx (with **Dugald Duncan** and **Hermann Brunner**)

$$2\pi \int_0^{t^n} J_0(|\omega|R) \hat{u}(\omega, t^n - R) dR = \hat{a}(\omega, t^n), \quad \omega \in \mathbb{R}^2$$

— first kind Volterra IE with smooth, oscillatory (convolution) kernel

$$2\pi \int_0^{t^n} J_0(|\omega|R) \hat{u}(\omega, t^n - R) dR = \hat{a}(\omega, t^n), \quad \omega \in \mathbb{R}^2$$

- Analysed **discontinuous Galerkin (DG)** approx – converges, but not quite as well as collocation. . .
- **DG result** for m th degree polynomials on intervals of size Δt :
 - global convergence: Δt^{m+1} for even m ; Δt^m for odd m
 - local superconvergence: Δt^{m+2} for even m (needs extra condition on exact solution); Δt^{m+1} for odd m
- **Collocation result:** (Brunner) – can always choose collocation points to give Δt^{m+1} global convergence and Δt^{m+2} local superconvergence

- Approx the BIE in space only (collocation):

$$\int_0^t Q(s) \underline{U}(t-t') dt' = \underline{a}(t), \quad t > 0$$

— matrix Q comes from the space approx

- System of 1st kind VIEs: use m th degree DG to approx in time
- (Spatial) Fourier “Stability coefficients” $p_n(\omega)$ are now $(m+1) \times (m+1)$ matrices
- $p_n(\omega)$ appear to be bounded for all frequencies (i.e. **stable**) for $m = 0, 1, \dots, 9$ (space approx is a Fourier interpolant)
- **But** scheme on a flat square plate looks **unstable** even for $m = 0$ (singular behaviour at corners?)

Galerkin in space, DG in time

- Approx u in space (Γ is unit square plate):

$$u(\mathbf{x}, t) \approx U(\mathbf{x}, t) = \sum_k U_k(t) \phi_k(\mathbf{x})$$

ϕ_k : global polynomial BFs in $\mathbb{P}^\nu(0, 1) \times \mathbb{P}^\nu(0, 1)$, $k = 1 : (\nu + 1)^2$

- Use **full Galerkin** in space – gives system of Volterra IEs:

$$\int_0^t Q(s) \underline{U}(t - t') dt' = \underline{a}(t), \quad t > 0$$

- **Result**: scheme appears stable for space degrees $\nu = 0, \dots, 36$ and DG0 in time.
- **Collocation** in space, DG0 in time is unstable

EM – perfect conductor

- **Rynne** (1999) well-posedness result for EFIE for smooth closed Γ
- **Terrasse** (PhD 1993) introduced functional framework for time dependent BIEs in EM problems
- **Michielssen** fast plane wave methods; singular edge behaviour; very impressive simulations; ...
- **Simulation**: scattering from a perfectly conducting narrow strip (1D model)

No dispersion at large distances

EM simulation

Scattering from a perfectly conducting narrow strip (1D model)

Shows 1D surface current

run

No dispersion at large distances.

Why time domain BIE?

- Can be implemented **more efficiently** than
 - full time domain PDE discretisation:

$$O(N^3 \log N) \quad \text{versus} \quad O(N^4)$$

on a $O(N \times N \times N)$ space domain over $O(N)$ time steps (Michielssen + team)

- frequency domain BIE (Nédélec)
- Mesh: only on the **surface**
- **No dispersion** in scattered field computation
- **But** theory and numerics much less well developed ...

Selected References

- A Bamberger, T Ha Duong: *Math. Meth. Appl. Sci.* **8**, 405–435 (1986)
- M Costabel: in *Encyclopedia of Computational Mechanics* Eds. E Stein et al, Wiley (2004)
- P J Davies, D B Duncan: *SINUM* **42**(3), 1167–1188 (2004)
- A A Ergin, B Shankar, E Michielssen: *J. Acoust. Soc. Am.* **107**(3) 1168–1178 (2000)
- T Ha Duong: in *Topics in Computational Wave Propagation* Eds. M Ainsworth et al, Springer (2003)
- Ch Lubich: *Num Math* **67**, 365–389 (1994)
- B P Rynne: *Math. Meth. Appl. Sci.* **22**, 619–631 (1999)